MUMUM q2vkpt Vulkan Path Trace Juake

LITTUM

Christoph Schied



http://brechpunkt.de/q2vkpt



Path Tracing

Number of samples, n=1 in q2vkpt



Main challenges



- Better Sampling \rightarrow less noise
- Denoising



Q2VKPT

- Research prototype to evaluate current state of real-time path tracing
- Open source https://github.com/cschied/q2vkpt
- Entirely raytraced
- Real-time path tracing (one indirect bounce)
- C99, Vulkan, GLSL, RTX

https://www.youtube.com/watch?v=vrq1T93uLag

frame time infrance: eenetry babupf gradient samples path tracer asvaf full asvaf temporal asvaf terous

	and the second se	and the second se
frame time	15.24	MS
instance geometry	0.02	MS
byh update	0.52	MS
asvgf gradient samples	0.28	MS
path tracer	10.89	MS
asvgf full	3.44	MS
asvgf reconstruct gradient	0.27	MS
asvgf temporal	0.68	MS
asvgf atrous	Z.16	MS
asvgf taa	0.32	MS

15.24 MS 0.02 MS 0.52 MS 0.28 MS 10.89 MS 3.44 MS 0.27 MS 2.16 MS 0.32 MS

2560x1440, RTX2080 Ti

- TO DO

A Completion

TITI

mill





Denoised result

minimizer

PTCC.

on the second second

1

Path tracer output (1spp)

Denoising (A-SVGF)



Gradient Estimation for Real-Time Adaptive Temporal Filtering

CHRISTOPH SCHIED, CHRISTOPH PETERS, and CARSTEN DACHSBACHER, Karlsruhe Institute of Technology, Germany



Fig. 1. Results of our novel spatio-temporal reconstruction filter (A-SVGF) for path tracing at one sample per pixel (cyan inset in frame 404) with a resolution of 1280×720. The animation includes a moving camera and a flickering, blue area light. Previous work (SVGF) [Schied et al. 2017] introduces temporal blur such that lighting is still present when the light source is off and glossy highlights leave a trail (magenta box in frame 412). Our temporal filter estimates and reconstructs sparse temporal gradients and uses them to adapt the temporal accumulation factor α per pixel. For example, the regions lit by the flickering blue light have a large α in frames 406 and 412 where the light has been turned on or off. Glossy highlights also receive a large α due to the camera movement. Overall, stale history information is rejected reliably.

Denoising (A-SVGF)



results, and a reference on two regions, and show the impact filtered global illumination has over just direct illumination. Given the noisy input, notice the similarity to the reference for glossy reflections, global illumination, and direct soft shadows.

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Main concepts of SVGF

Analyze input over time

- Temporally unstable \rightarrow blur more
- Temporally stable \rightarrow blur less



Filter hierarchically, starting small

- Estimate temporal stability after each filter iteration
- → Strong blur more likely in early iterations

SVGF



Edge-avoiding À-trous Wavelets

$\begin{array}{c} \bullet & \bullet & \bullet & \bullet & \bullet & \bullet & \hat{c}_i(q) \\ & & & & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & \\ & &$

$$\hat{c}_{i+1}(p) = \frac{\sum_{q \in \Omega} h(q) \cdot w(p,q) \cdot \hat{c}_i(q)}{\sum_{q \in \Omega} h(q) \cdot w(p,q)}$$

In q2vkpt:

- 3x3 box kernel
- 5 iterations

https://www.youtube.com/watch?v=Fv-jStEsCpE&t=48s

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SVGF



Denoising (A-SVGF)



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Screen-space Reprojection



Current frame c_i

Previous filtered frame \hat{c}_{i-1}

$$\hat{c}_i(x) = \alpha \cdot c_i(x) + (1 - \alpha) \cdot \hat{c}_{i-1}(x)$$

Adaptive Temporal Filtering

$$\hat{c}_i(x) = \alpha \cdot c_i(x) + (1 - \alpha) \cdot \hat{c}_{i-1}(x)$$

- Set α according to changes of the shading function
 - Moving shadows, glossy highlights, flickering light sources, ...
- Make α per-pixel weight for local adaptivity
- Need information about changes of shading (temporal gradient)

Path tracer output 1 sample per pixel



Difference of luminance green positive red negative



Path tracer output 1 sample per pixel



Difference of luminance green positive red negative



Path tracer output 1 sample per pixel (correlated samples)

Difference of luminance (correlated samples) green positive red negative

Adaptive temporal filter weight

Reconstructed temporal gradien	t
Adaptive filter weight α	

• Sample and reconstruct temporal gradient

• Change α according to relative rate of change

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https://www.youtube.com/watch?v=HP4Xwp0ETfc





Treat each triangle of light meshes as individual area light

Light selection / sampling

Tried:

• Light hierarchy

Issues:

- Speed
- Inconsistent quality under animation



Importance Sampling of Many Lights with Adaptive Tree Splitting

ALEJANDRO CONTY ESTEVEZ, Sony Pictures Imageworks CHRISTOPHER KULLA, Sony Pictures Imageworks



Fig. 1. A procedural city with 363,036 lights, one Gl bounce and participating media. Rendered with 16 samples per pixel, each shading point takes an average of 7 shadow rays (45 for the volume integral). We shoot an average of 1700 rays per pixel. The image rendered in 20 minutes on a quad core Intel i7.

We present a technique to importance sample large collections of lights (including mesh lights as collections of small emitters) in the context of Monte-Carlo path tracing. A bounding volume hierarchy over all emitters is traversed at each shading point using a single random number in a way that importance samples their predicted contribution. The tree aggregates energy, spatial and orientation information from the emitters to enable accurate prediction of the effect of a cluster of lights on any given shading point. We further improve the performance of the algorithm by forcing splitting until the importance of a cluster is sufficiently representative of its contents.

 $\label{eq:ccs} \text{CCS Concepts:} \bullet \textbf{Computing methodologies} \to \textbf{Ray tracing};$

Additional Key Words and Phrases: illumination, ray tracing, many lights

ACM Reference Format:

Alejandro Conty Estevez and Christopher Kulla. 2018. Importance Sampling of Many Lights with Adaptive Tree Splitting. Proc. ACM Comput. Graph. Interact. Tech. 1, 2, Article 25 (August 2018), 17 pages. https://doi. org/10.1145/3233305

1 INTRODUCTION

Direct lighting calculations are a critical part of modern path tracing renderers with next event estimation. While sampling from simple light shapes [Shirley et al. 1996] is well understood, relatively little attention has been devoted to the problem of efficiently sampling from large collections of such shapes. In production renderers, this problem appears both in the form of scenes containing many distinct lights (Figure 1), and scenes with meshes acting as emitters (sometimes

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Light selection



Path tracer

- One path per pixel
- One indirect bounce
- Two shadow rays



No explicit Environment Map sampling

- Use indirect bounce
- No illumination for indirect bounce (missing raycast)

Constant Blinn-Phong BRDF for everything



Mirror reflection

- No transmission
- Demodulate indirect albedo
- Fixed lower mip-level for texture sampling









Source: http://momentsingraphics.de/?p=127

Blue noise





Source: http://momentsingraphics.de/?p=127

Magnitude of Fourier Transform



Source: http://momentsingraphics.de/?p=127



Acceleration structures



Forward / Backward projection

- Required for Adaptive Temporal Filtering
- Visibility buffer for forward projection
- Map instances between frames



Conclusion

- Real-time path tracing is possible (in the near future)
- Transition difficult
 - Random access to everything
 - Tweaking of assets
- Need more research specifically tailored towards real-time rendering
 - Fast and robust importance sampling
 - Denoising

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NVIDIA id Software

Thanks!

Q2VKPT uses a texture addon collected by Tosher including original work by D Scott Boyce (@scobotech), released under Creative Commons Attribution-NonCommercial-ShareAlike 2.0



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